

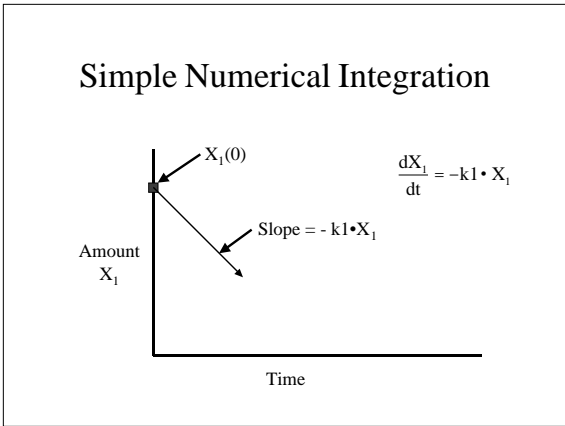
Numerical Integration

Numerical Integration

- Objectives:
 - Understand the process of Numerical Integration
 - Understand some of the Numerical Integration methods (algorithms)
 - Consider the Advantages and Disadvantages of some these methods

Numerical Integration Methods

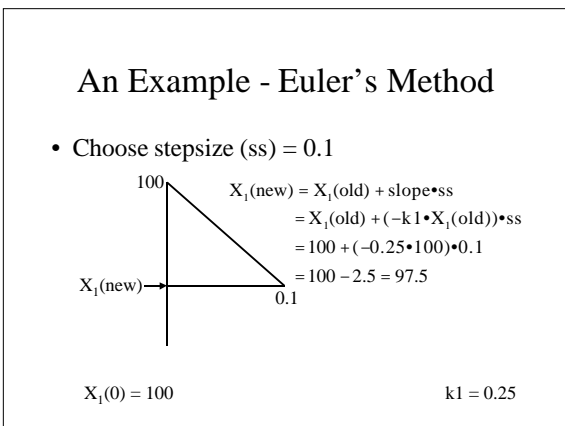
- Point-slope (Euler's) Method
 - Step-Size
- Runge-Kutta Methods
- RKF45 Method
- Predictor-Corrector Method
- Gear's Method



Point-Slope (Euler's) Method

- Point-Slope Method
- Point
 - Initial Value - $X_1(0)$
- Slope
 - Differential Equation - $k_1 \cdot X_1$

The Equation $\frac{dX_1}{dt} = -k_1 \cdot X_1$



An Example - Euler's Method

Time	ΔX_1	X_1
0.0		100
0.1	-2.50	97.50
0.2	-2.44	95.06
0.3	-2.38	92.68
0.4	-2.32	90.36
0.5	-2.26	88.10

$X_1(0) = 100$

$k_1 = 0.25$

Euler's Method

$$\frac{dC_p}{dt} = -k_{el} \cdot C_p$$

$$t_1 = t_0 + \Delta t$$

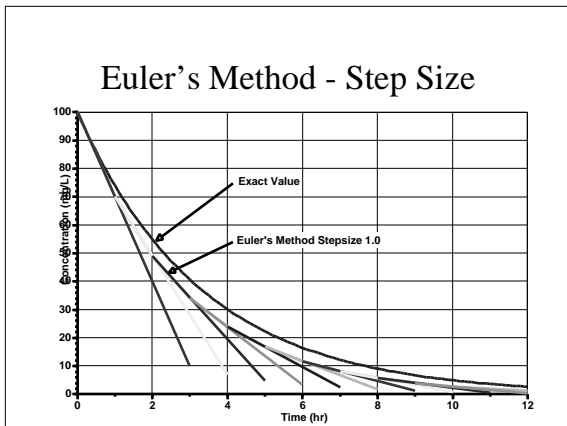
$$C_{p1} = C_{p0} + \frac{dC_p}{dt} \cdot \Delta t$$

Euler's Method

• Another Example

– C_{p0} 100 mg/L and $k_{el} = 0.3 \text{ hr}^{-1}$

Stepsize	Numerical	Analytical	% Error	Number of Steps
1	70.0	74.08	5.51	1
0.5	85.0	86.07	1.24	2
0.25	92.5	92.77	0.30	4
0.1	97.0	97.04	0.05	10



Euler's Method

- Simple mathematically
- Requires small step size for accuracy

Runge-Kutta Method

- Fourth Order

$$C_1 = C_0 + \frac{1}{4} (k_1 + 3k_2 + 3k_3 + k_4)$$

$$k_1 = \Delta t \cdot f(t_0, C_0) = -k_{el} \cdot C_0 \cdot \Delta t$$

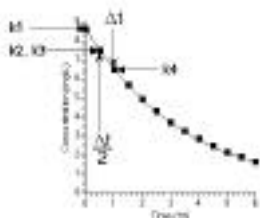
$$k_2 = \Delta t \cdot f(t_0 + \frac{\Delta t}{2}, C_0 + \frac{k_1}{2})$$

$$k_3 = \Delta t \cdot f(t_0 + \frac{\Delta t}{2}, C_0 + \frac{k_2}{2})$$

$$k_4 = \Delta t \cdot f(t_0 + \Delta t, C_0 + k_3)$$

Runge-Kutta Method

- Fourth Order



Runge-Kutta Method

- $C_{p0} = 100 \text{ mg/L}$ and $k_{el} = 0.3 \text{ hr}^{-1}$

Stepsize	Numerical	Analytical
1	74.084	74.082
0.5	86.071	86.071
0.25	92.774	92.774
0.1	97.044	97.045

- More Accurate with Four Evaluations per step
- No Automatic Stepsize Control

Runge Kutta Fehlberg

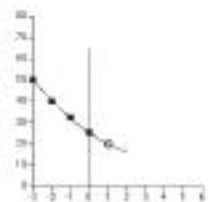
- RKF45
 - Fifth Evaluation used to give Automatic Stepsize Adjustment
 - Very Efficient for Typical Pharmacokinetic Systems
 - Use this Method as default with Boomer

Predictor-Corrector Methods

- Adam's Method and variations
 - Larger Stepsize Possible
 - More Complex Calculations

Predictor-Corrector Method

- Adam's Method



Predictor-Corrector

- Gear's Method
 - Very Efficient for 'Stiff' Systems
 - 'Stiff' Systems include Both Very Fast and Very Slow Processes (Rate constants)
 - Difference between Fastest and Slowest Extreme

$$\frac{k_{\text{fastest}}}{k_{\text{slowest}}} = 500$$

Numerical Integration

- Comparison between Numerical Integration Methods

	Runge Kutta	RKF45	Adam's	Gear's
ka/ke1 1.0	15	2	2	2
ka/ke1 10	38	2	3	4
ka/ke1 100	174	7	14	4
ka/ke1 1000	*	50	110	4



Numerical Integration

- Boomer
 - RK, RKF45, Adams', Gear's
- SAAM II
 - Rosenbrock (Stiff), RKF45, Pade (Special)
- WinNONLIN
- ADAPT
 - LSODA (Switches between Adam's and Gear's Method)
